



# Disruption

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What is the disruption?

Where disruption is probable to occurs?

What is the physical mechanism of the disruption?

How to avoid or mitigate the disruption?



**Disruption** is a rapid loss of plasma confinement.

- The stored energy in tokamak is approximately proportional to  $L^5$  (where L is a linear dimension of the plasma)
- The energy dissipated in the wall in this case proportional to  $L^3$
- <u>Conclusion</u>: Doubling the size of the device (JET to ITER) increases energy load by one order of magnitude. If this energy is lost, we have problems.....

## **PROBLEMS**:

- Heat loads
- Mechanical loads

## Disruptions get more severe in bigger tokamaks



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## How disruption look like?



Pictures of JET during a disruption. A cloud of particles is visible in the vessel's lower half (left) and upper half (right).

It is clear that disruption is an extreme event which has to be avoided, at least in its most dangerous form.

# The JET disruption



Tokamak operated normally after this event!

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# Disruptions are a survivable event



- Tokamaks can be designed to withstand them
- They can be largely avoided (e.g. the shots used for D-T operation in TFTR had <1% disruptivity) and their consequences mitigated
- Most of the examples I show are deliberately induced for the purposes of studying disruption physics



# Statistics from JET for the operational period from 2000 to 2007

[P.C. de Vries et al., Statistical analysis of disruptions in JET. Nucl. Fusion49, 055011 (2009)]



# $Greenwald limit \qquad q_a = \frac{2\pi a^2 B_z}{\mu_0 I_p R} \ge 3$

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# The Hugill diagram and the main limits for plasma operations

[V. Igochine, "Active Control of Magneto-hydrodynamic Instabilities in Hot Plasmas", Springer, 2015]





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## Disruption becomes much more probable close to the operation limits!

# **Classical disruption picture**

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# A common limit is radiative



# Radiative collapse leads to unstable J(r)



• Kink instability when effective q<sub>edge</sub>=2

or

• Tearing destabilised by dJ/dr within q=2 (see NTM lecture)  $\frac{d^2\psi}{dr^2} - \frac{C(r)dJ/dr}{r-r_s} = 0$ 

q=2 Minor radius

## Classical picture - energy loss is stochastic

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# Forces – Halo currents



Also decaying moving plasma drives vessel eddy currents

(because halo flow along field line)

# +ve Ip and -ve loop voltage spike



Standard explanation (Wesson):-

• Conservation of magnetic energy  $(LI_p^2/2)$  and internal inductance drop (J-flattening)  $\Rightarrow I_p$  increases  $\Rightarrow$  -ve  $V_{loop}$ 

Hiro current (Zakharov NF 2010):-

• VDE causes negative surface current, which when transferred into wall  $\Rightarrow I_p$  rises

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# **Classical disruption picture**

ΡΡ



# Disruption causes – not simple!

Flow diagram\* of all 1654 unintentional JET disruptions between 2000-2010+



\*The arrow width gives the frequency this sequence occurred in the cause database

<sup>+</sup> P.C. de Vries et al, Nucl Fus 2011

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# Disruption causes

- A survey of disruption causes at JET found that the most common disruption causes were neo-classical tearing modes, human error and density/impurity/shape control: >50% were caused by technical issues
- The JET disruption rate decreased significantly over the years





Key issues to be resolved for disruptions:

- Forces
- Heat Loads
- Runaways
- Mitigation
- Prediction and avoidance







 Forces (VDE symmetric load ~100MN, asymmetric ~40MN)



# Halo currents not always symmetric



ASDEX Upgrade have cases with different currents in different sectors!

## G Pautasso et al

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## Halo currents not always symmetric



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## Current Asymmetries – wall touching kink mode



- Plasma moves up in VDE and shrinks ⇒ boundary-q decrease
- When q<sub>a</sub>=1 external kink mode



- In an external kink mode a helical surface current (termed Hiro current) flows
- On the side moving towards the wall the Hiro current is against  ${\rm I}_{\rm p}$

#### From L Zakharov PoP 2008

## Forces – Halo and Eddy currents both important



Each tokamak has its own engineering limits for maximal symmetric and asymmetric forces. This is defined already on the first design stage.

#### M Sugihara et al, Nucl Fusion 2007

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# Heat Loads





Large areas receive >10MJ/m<sup>2</sup>  $\Rightarrow \mathcal{E} = 180 \text{ MJ/m}^2/\text{s}^{0.5}(\Delta t = 3ms);$  $\varepsilon_{melt} \approx 28 \text{ MJ/m}^2/\text{s}^{0.5}$ 

Sets targets for mitigation!

• Limiter Scrape-Off Layer expansion during disruption needs study

The term Scrape-Off Layer (SOL) refers to the plasma region characterized by open field lines. \*With limiter plasmas, this region is the region outside the Last Closed Flux Surface (LCFS). \*With divertor plasmas, this region is the region outside the separatrix. Runaways

## •Runaways (~10MA at 10-20MeV)





Examples from JET



# **Runaway** electrons

G98.576/11c



- Disruptions: quick cooling of the plasma (thermal quench TQ)
- Current quench (CQ) as the resistivity is increased (R ~ T<sup>-3/2</sup>)
  - ⇒ Ip cannot drop arbitrarily fast toroidal electric field is induced



- Runaway electrons (RE) can be generated with O(MA) current
  poses a great risk to plasma facing components = JET 2014
- Runaway generation: complex dependence on Etor, ne, Te, Zeff, ...
  Need to understand the self-consistent evolution of all



2015-09-10 Stochasticity in Fusion Plasmas Gergely Papp

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runaway control / suppression

Michael Lehnen | Institute of Energy Research - Plasma Physics | Association EURATOM - FZJ



#### ITER Needs

Most demanding requirement for mitigation: Heat loads during thermal quench and from runaway electrons

Three key elements:

- (1) Disruption rate;  $\leq$  3% (Avoidance)
- (2) Prediction success rate;  $\geq$  95% (Prediction)
- (3) Heat flux mitigation by DMS;  $\leq 1/10$  (Mitigation)

All these three target values must be satisfied simultaneously to meet the requirement for lifetime (2-3 times replacements during life)

M. Sugihara, ITPA-MDC March 2011





Type of shutdown	Unintentional disruptions	
Mode Lock	630	48.4%
echnical (PPCC, SC, etc.)	304	23.4%
MHD mode	40	3.1%
None	327	25.1%

only a few of the detected disruptions (~20%) have a warning time < 100ms

P. de Vries, NF 2009





#### But

gas injection is not always the best choice

locked mode detection does not always allow enough reaction time

in many cases other events are the root cause bringing the plasma onto the path to mode lock and eventually to disruption

detection of a single pre-cursor does not ensure safe prediction of a disruption

G. Pautasso, NF2007

Neural Networks (NNs) are a family of models inspired by biological neural networks (the central nervous systems of animals, in particular the brain) which are used to estimate or approximate functions that can depend on a large number of inputs and are generally unknown. (We use it for the disruption because we do not know the exact physics!)

<u>Pro:</u> It works well <u>Contro</u>: (1) It is almost impossible to transfer (2) It needs to be trained and we can not do disruptions for this purpouse in ITER



**Fig. 7.11** Performance of a NN trained on ASDEX Upgrade and applied to JET. Also shown is the performance of the network on ASDEX Upgrade. From [48]



External coils suppress the mode.

(The same idea as for resistive wall mode control)

**Fig. 7.12** Two nominally identical pulses with **a** magnetic feedback applied from 240 ms and **b** no feedback. The feedback lowers the magnetic fluctuation amplitude (dB/dt) and allows a higher density to be achieved. From [68], copyright 1990 by the American Physical Society





As soon as the disruption precursor signal (the locked mode detector and/or the loop voltage) reaches the preset threshold, the Electron Cyclotron Resonance Heating (ECRH) poweris triggered by real-time control and heat the island.

**Figure 1.** (top) Reference disruption at high  $\beta_N$ : time traces of  $I_p$ ,  $P_{NBI}$ ,  $P_{ECRH}$ ,  $\beta_N$ , Mirnov coil signal and locked mode (LM) detector signal with its thresholds. (bottom) Same discharge repeated with injection of ECRH ( $\rho_{dep} \sim 0.5$ ) real-time triggered by LM.



After a short flight time for injected gas the edge electron temperature ('edge Te') drops and then the outer region of the plasmas cools causing a drop in the plasma thermal energy (Eth), this is followed by a rapid loss of plasma energy (as shown by the central Soft X-ray) known as the thermal quench.

The three aims of MGI are:

- to reduce disruption heat loads to surrounding components,
- to reduce disruption EM forces
- to mitigate runaways.

Reduction of heat loads is achieved by the MGI increasing the radiated power fraction, which spreads the heat loads more uniformly.



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#### Disruption mitigation – gas puff







An alternate scheme for disruption mitigation, that pre-dates MGI, is by the injection of frozen gas killer pellets. As with Massive Gas Injection, the killer pellets were successful in mitigating heat loads and halo currents, but there was a tendency to produce runaway electrons



Hollmann *et al.* Phys. Plasmas **22**, 021802 (2015)



Disruption is .....

Disruption becomes much more probable close to ....

Typical sequences of the disruption:...

Disruption problems:

• ...



Disruption is a rapid loss of plasma confinement.

Disruption becomes much more probable close to the operation limits.

Typical sequences of the disruption: Approach the operational limit  $\rightarrow$  instability  $\rightarrow$  energy losses  $\rightarrow$  plasma toches the wall  $\rightarrow$  plasma cooling  $\rightarrow$  lost of current

Disruption problems:

- Forces
- Heat Loads
- Runaways



Disruption detection:

• ...

Actions which can be done to avoid or mitigate the disruption:

• ...



Disruption detection:

- Lock mode sensor (magnetic coils)
- Neural network

Actions which can be done to avoid or mitigate the disruption:

- Magnetic control of the mode
- ECRH
- Gas puff
- Pellet